## PE29102

### **Document Category: Product Specification**



## UltraCMOS® High-speed FET Driver, 40 MHz

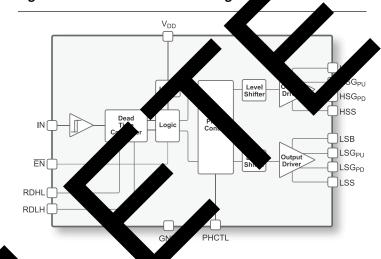
#### **Features**

- · High- and low-side FET drivers
- · Dead-time control
- · Fast propagation delay, 9 ns
- · Tri-state enable mode
- · Sub-nanosecond rise and fall time
- · 2A/4A peak source/sink current
- · Package flip chip

## **Applications**

- · Class D audio
- DC–DCconversions
- · AC-DC conversions
- · Wireless charging
- · Envelope tracking
- LiDAR

#### Figure 1 • PE29102 Functional Diagram



## **Product Description**

gh-speed drive The PE29102 is an integrated to control the gates of external power devices, such FETs. The outputs of the PE29102 are capable of providing as enhancement mode galling nitride ( switching transition speeds and range for switching applications up to 40 MHz. The PE29102 is optimized for matched dead and offers est-in-class propagation delay to improve system bandwidth. High switching spe ult in smaller peri ral components and enable innovative designs for applications such as class D The PE29102 is available in a flip chip package. wireless

The PE29103 manufactor in Peregrine's UltraCMOS process, a patented advanced form of silicon-on-insulator (SOI) through y, offer the performance of GaAs with the economy and integration of conventional CMOS.

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Product Specification DOC-81227-7 – (11/2018)



## **Absolute Maximum Ratings**

Exceeding absolute maximum ratings listed in **Table 1** may cause permanent damage. Operation should be restricted to the limits in **Table 2**. Operation between operating range maximum and absolute maximum for extended periods may reduce reliability.

#### **ESD Precautions**

When handling this UltraCMOS device, observe the same precautions as with any other ESE ensitive devices. Although this device contains circuitry to protect it from damage due to ESD, precautices should aken to avoid exceeding the rating specified in **Table 1**.

### Latch-up Immunity

Unlike conventional CMOS devices, UltraCMOS devices are immune to lath-up.

Table 1 ■ Absolute Maximum Ratings for PE29102

Parameter/Condition	Min	Max	Unit
Low-side bias (LSB) to low-side source (LSS)	-0.5	7	V
High-side bias (HSB) to high-side source (HSS)	ß	7	V
Input signal	-0.3	7	V
HSS to LSS	-100	100	V
HSS to GND	-1	100	V
LSS to GND	-1	100	V
ESD voltage HBM <sup>(*)</sup> , all pins		500	V
Note: * Human body model (JEDEC JS-2000) 2A).			

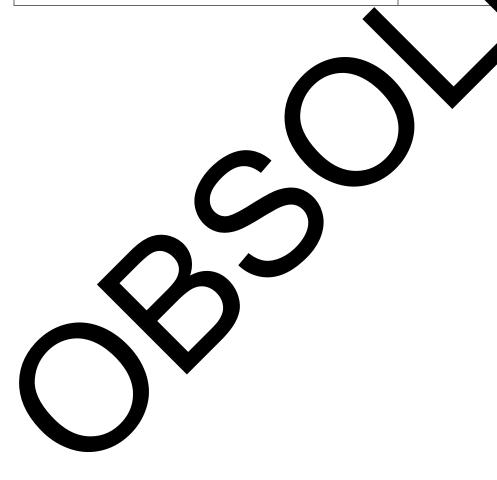


# **Recommended Operating Conditions**

**Table 2** lists the recommended operating conditions for the PE29102. Devices should not be operated outside the recommended operating conditions listed below.

Table 2 ■ Recommended Operating Conditions for PE29102

Parameter	Min	Тур	Max	Jnit
Supply for driver front-end, V <sub>DD</sub>	4.0	5.0	0	V
Supply for high-side driver, HSB	4.0	5.0	6.	
Supply for low-side driver, LSB	4.0		6.0	V
HIGH level input voltage, VIH	1.6		6.0	V
LOW level input voltage, VIL	0		0.6	V
HSS range	0		0	V
LSS range			60	V
Operating temperature	-40		+105	°C
Junction temperature	-40		+125	°C



DOC-81227-7 – (11/2018) Page 3 of 16



# **Electrical Specifications**

**Table 3** provides the key electrical specifications @ +25 °C, V<sub>DD</sub> = 5V, 100 pF load, HSB and LSB bootstrap diode included unless otherwise specified.

Table 3 ■ DC Characteristics

Parameter	Condition	Min	Тур	Max	Jnit
DC Characteristics					
V <sub>DD</sub> quiescent current	V <sub>DD</sub> = 5V		ß		m
HSB quiescent current	V <sub>DD</sub> = 5V			ıA.	
LSB quiescent current	V <sub>DD</sub> = 5V		2.7		mA
Total quiescent current	V <sub>DD</sub> = 5V		6.7	9.0	mA
V <sub>DD</sub> quiescent current	V <sub>DD</sub> = 6V		1.6		mA
HSB quiescent current	V <sub>DD</sub> = 6V		3.6		mA
LSB quiescent current	V <sub>DD</sub> = 6V		3		mA
Total quiescent current	V <sub>DD</sub> = 6V		J.0	11.6	mA
Under Voltage Lockout					
Under voltage release (rising)			3.6	3.8	V
Under voltage hysteresis			400		mV
Gate Drivers					
HSG <sub>PU</sub> /LSG <sub>PU</sub> pull-up resistance			1.9		Ω
HSG <sub>PD</sub> /LSG <sub>PD</sub> pull-down resistance			1.3		Ω
HSG <sub>PU</sub> /LSG <sub>PU</sub> leakage current	USG <sub>PU</sub> V, LSB-LSG = 5V		10		μA
HSG <sub>PD</sub> /LSG <sub>PD</sub> leakage current	HSG <sub>PD</sub> -HSS = 5V, LSS = 5V		10		μA
Dead-time Control			I		
Dead-time control voltages	κΩ resistor		1.3		V
	RDHL = 30 k		1.9		ns
Dead-time from by going love	RΔ κΩ		7.0		ns
LSG going high	RDHL = 150 kΩ		13.6		ns
	DHL = 255 kΩ		23.5		ns
	RDLH = 30 kΩ		1.8		ns
Cond-time from Ls roing is	RDLH = 80.6 kΩ		6.7		ns
G going high	RDLH = 150 kΩ		13.2		ns
	RDLH = 255 kΩ		22.7		ns
Sharp Characteristics					
LSG to gation delay	At min dead time		9.1		ns
HSG rise time	10 - 90% with 100pF load		0.9		ns
LSG rise time	10 - 90% with 100pF load		0.9		ns
HSG fall time	90 - 10% with 100pF load		0.8		ns
LSG fall time	90 - 10% with 100pF load		0.9		ns



#### Table 3 ■ DC Characteristics (Cont.)

Parameter	Condition	Min	Тур	Max	Unit
Minimum output pulse width			2.8	5.0	ns
Max switching frequency @ 50% duty cycle	RDHL = RDLH = 80 kΩ	40			MHz

# **Control Logic**

Table 4 provides the control logic truth table for the PE29102.

Table 4 ■ Truth Table for PE29102

EN	IN	HSG <sub>PU</sub> -HSS	HSG <sub>PD</sub> -HSS	LSG <sub>PU</sub> -LSS	LSG <sub>PD</sub> -LSS
L	L	Hi–Z	L	<b>→</b> H	Hi–Z
L	Н	Н	Hi-	Hi–Z	L
Н	L	Hi–Z	L	Hi–7	L
Н	Н	Hi–Z	L	1	L





# **Typical Performance Data**

**Figure 2** through **Figure 4** show the typical performance data @ +25 °C,  $V_{DD}$  = 5V, load = 2.2Ω resistor in series with 100 pF capacitor, HSB and LSB bootstrap diode included, unless otherwise specified.

Figure 2 • Total Quiescent Current (mA)

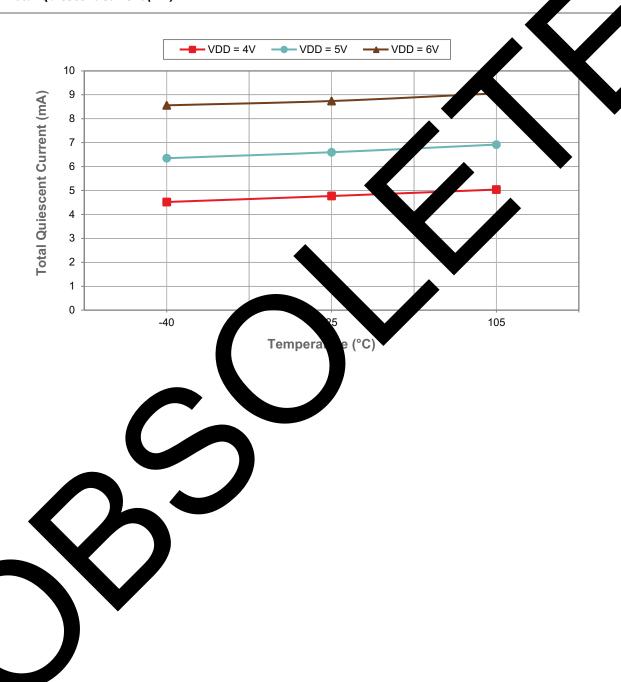




Figure 3 • UVLO Threshold (V)

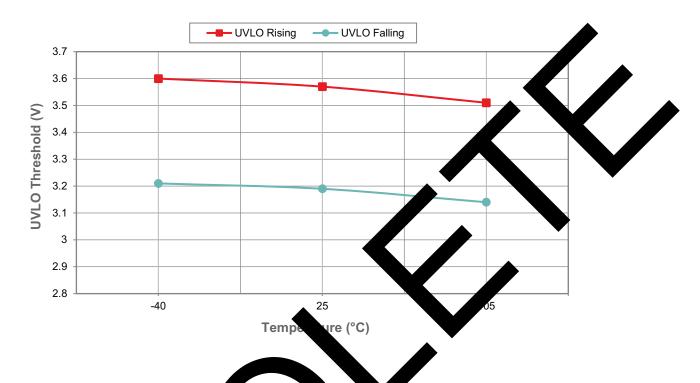
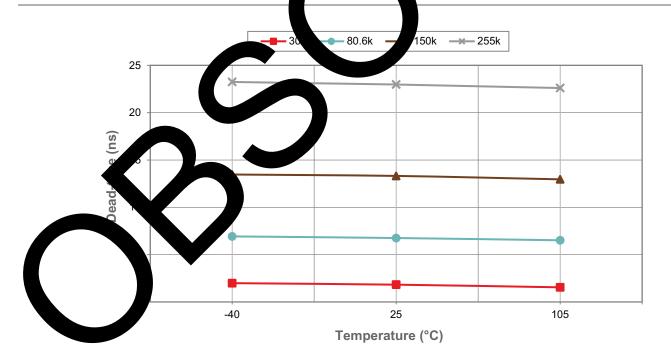


Figure 4 • Dead-time (ns)



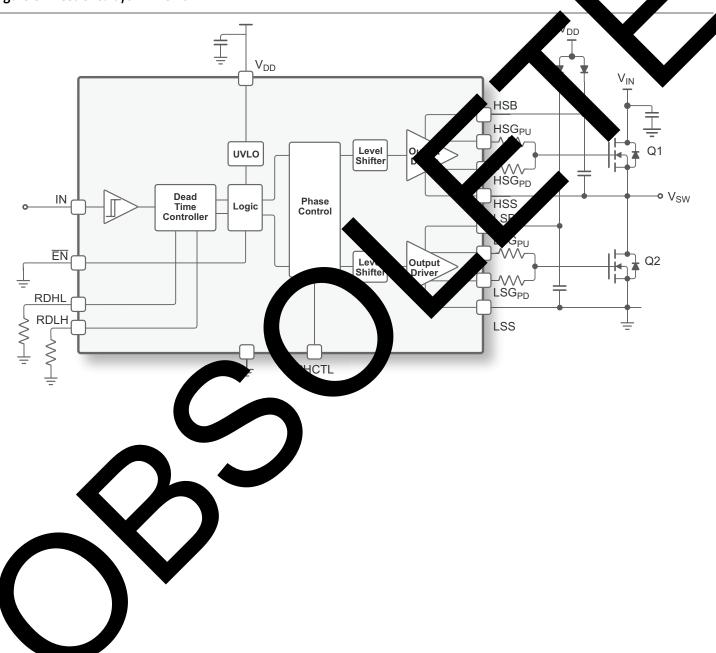
DOC-81227-7 – (11/2018) Page 7 of 16



# **Test Diagram**

**Figure 5** shows the test circuit used for obtaining measurements. The two bootstrap diodes shown in the schematic are used for symmetry purposes in characterization. In practice, only the HSB diode is required. Removing the LSB diode will result in higher low-side supply voltage since the diode drop is eliminated. As a result, the dead-time resistor can be adjusted to compensate for any changes in propagation dead.

Figure 5 • Test Circuit for PE29102





### Theory of Operation

#### General

The PE29102 is intended to drive both the high-side (HS) and the low-side (LS) gates of external rower FETs, such as enhancement mode GaN FETs, for power management applications. The PE29102 is such different tions requiring higher switching speeds due to the reduced parasitic properties of the high resolutions substrate inherent with Peregrine's UltraCMOS process.

The driver uses a single-ended pulse width modulation (PWM) input that feeds a dead the country, capable of generating a small and accurate dead-time. The dead-time circuit prevents shoot a ough curry in the output stage. The propagation delay of the dead-time controller must be small to reach the fast switch as recorrements when driving GaN FETs. The differential outputs of the dead-time controller are seen level-shifter om a low-voltage domain to a high-voltage domain required by the output drivers.

Each of the output drivers includes two separate pull-up and pull-down or puts allowing independent control of the turn-on and turn-off gate loop resistance. The low impedance output of the drivers improve external power FETs switching speed and efficiency, and minimizes the effects of the voltage of time (dv/dt) transients.

### **Under-voltage Lockout**

An internal under-voltage lockout (UVLO) feature prevents the PE29102 has powering up before input voltage rises above the UVLO threshold of 3.6V (typ), and 400 V (typ) of hysteresis and ilt in to prevent false triggering of the UVLO circuit. The UVLO must be cleared and the EN pin must be released before the part will be enabled.

### Dead-time Adjustment

The PE29102 features a dead-time adjustment that allows to user to control the timing of the LS and HS gates to eliminate any large shoot-through current which could comatically reduce the efficiency of the circuit and potentially damage the GaN FETs. Two external resistors of trol the timing of outputs in the dead-time controller block. The timing was forms are illustrated in the damage to the controller block.

The dead-time resistors only dge of the low-side gate (LSG) and high-side gate (HSG) outputs. ffect the ge of HSG, thus providing the desired dead-time between LSG Dead-time resistor RDLH will falling and HSG rising. Likewis stor RDHL will delay the rising edge of LSG, thus providing the ad-time re desired dead-time HSG falling and G rising. Figure 7 shows the resulting dead-time versus the external resistor bias diode/capacitors installed as indicated in Figure 5. The LS iues w apacitor. ded for symmetry only and are not required for the part to function. Removing bias diode an the LS bias did  $_{ t LSG}$  voltage by approximately 0.3V, resulting in a wider separation of the  ${ t t}_{ t DHL}$ ease th and t<sub>DLH</sub> curves in re 7.

#### Plase Control

Fig. 10 (PHCTL) coursels the polarity of the gate driver outputs. When PHCTL is low, the HSG will be in phase the input signs. When PHCTL is high, the LSG will be in phase with the input signal. The PHCTL pin includes an interresponding of the polarity of the gate driver outputs. When PHCTL is low, the HSG will be in phase with the input signal. The PHCTL pin includes an interresponding of the gate driver outputs. When PHCTL is low, the HSG will be in phase with the input signal. The PHCTL pin includes an interresponding of the gate driver outputs.

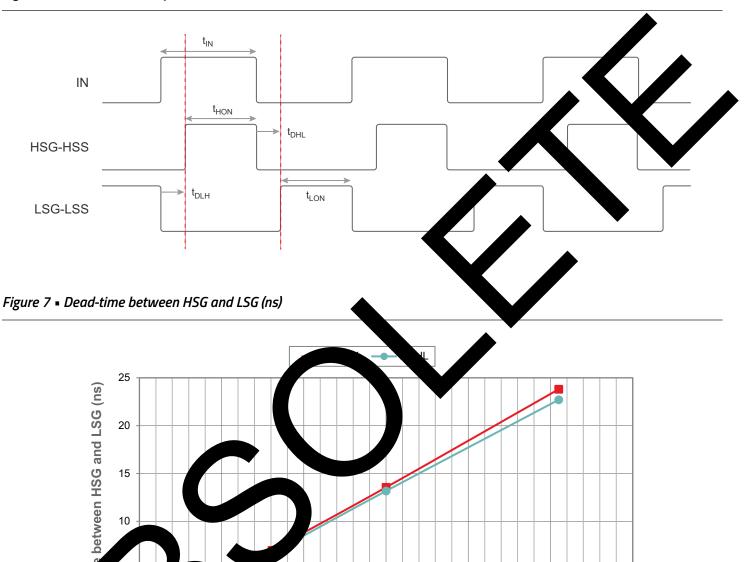
DOC-81227-7 – (11/2018) Page 9 of 16



Figure 6 and Figure 7 provide the dead-time description for the PE29102.

Figure 6 • Dead-time Description

10



150

Dead-time Resistance (kΩ)

200

250

300

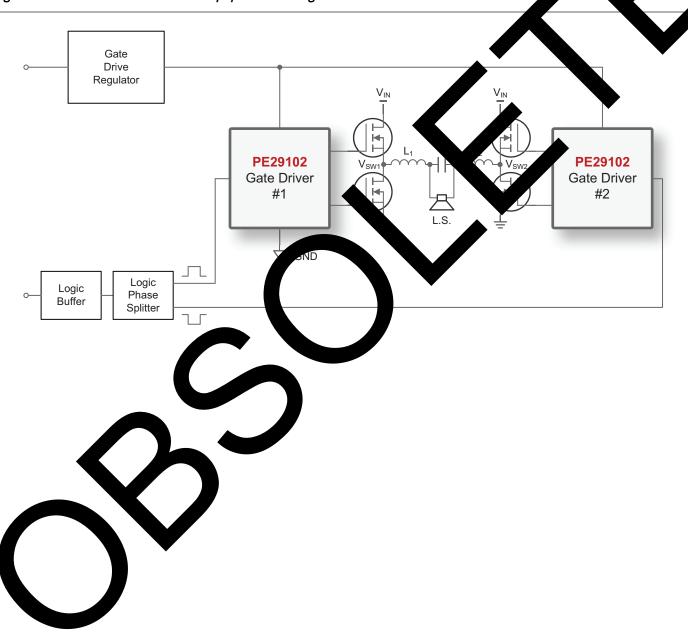
100



### **Application Circuit**

Figure 8 shows a class-D audio amplifier application diagram using two PE29102 gate drivers in a full-bridge configuration. The full-bridge circuit comprises two half bridge topologies that share a common supply and load. The low-level logic circuitry is powered by the gate drive regulator that supplies the PE29102 drivers ogic buffer and phase splitter. The PWM input signal feeds a single logic buffer, which drives a common logic x-OR gate Phase Splitter that provides phase inverted signals to each driver. VIN is designed to operate 50V DC (max.) to provide between 100 — 120W of power into an 8Ω load.

Figure 8 • PE29102 Class D Audio Amplifier Block Diagram





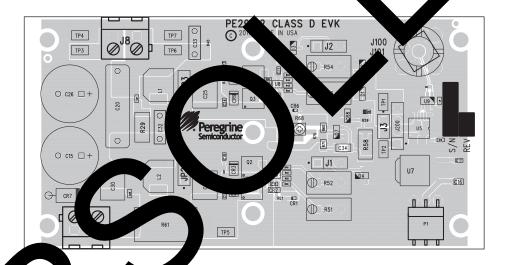
### **Evaluation Board**

The PE29102 evaluation board (EVB) allows the user to evaluate the PE29102 gate driver in either a full-bridge configuration or two independent half-bridge configurations. The EVB is assembled with two PE29102 FET drivers and four GS61004B E-mode GaN FETs. Refer to Peregrine Semiconductor DOC-82956 for mation.

Because the PE29102 is capable of generating fast switching speeds, the printed circuit boars (PCB) lay at is a critical component of the design. The layout should occupy a small area with the power FE cand extend bypass capacitors placed as close as possible to the driver to reduce any resonances a social by the gate loops, common source and power loop inductances. Since the maximum allowable of e-to-source foltage for the GS61004B FETs is 7V, resonance in the gate loops can generate ringing that the degrade the power devices due to high voltage spikes. Additionally, it is apportant to keep bound paths short.

The PCB is fabricated on FR4 material, with a total thickness of 0.062 in res. A minimum of the thickness of 1.5 ounces or more is recommended on the PCB outer layers to limit a stive losses and implice thermal spreading.

Figure 9 ■ PE29102 Evaluation Board Assembly





# **Pin Configuration**

This section provides pin information for the PE29102. **Figure 10** shows the pin map of this device for the available package. **Table 5** provides a description for each pin.

Figure 10 ■ Pin Configuration (Top View-Bumps Down)

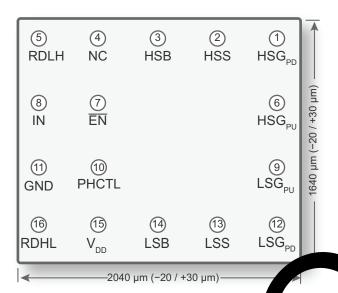


Table 5 ■ Pin Descriptions for PE29102

	•	,
Pin No.	Pin Name	Descrit .on
1	HSG <sub>PD</sub>	High-side gate vive pull-d
2	HSS	High-si source
3	HSB	Hi de bias
4	NC •	to con. sion (ground or fix
5	<b>∠</b> H	Dead-time & rol resistor sets LSG falling to HSG and delay (external resistor to GND)
6	HSG <sub>PI</sub>	High-side gate drive pull-up
7 <sup>(*)</sup>		Enable raive low, tri-state outputs when high
8(*)	IN	Introl input
9	LSG	Low-side gate drive pull-up
10	ACTL	Controls the polarity of the gate driver outputs
11	GND	Ground
12	LSG <sub>PD</sub>	Low-side gate drive pull-down
13	LSS	Low-side source
14	LSB	Low-side bias
15	$V_{DD}$	+5V supply voltage
16	RDHL	Dead-time control resistor sets HSG falling to LSG rising delay (external resistor to ground)
Note: * Interr	nal 100k pull d	own resistor

DOC-81227-7 – (11/2018) Page 13 of 16



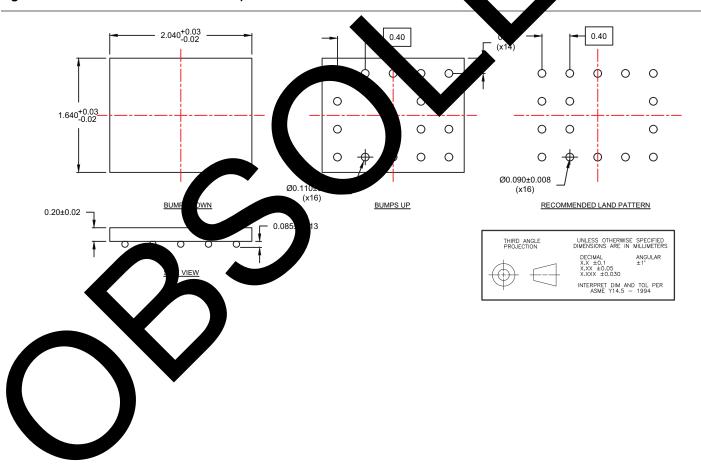
# **Die Mechanical Specifications**

This section provides the die mechanical specifications for the PE29102.

Table 6 ■ Die Mechanical Specifications for PE29102

Parameter	Min	Тур	Max	Unit	Tes condition
Die size, singulated (x,y)		2040 × 1640		μm	In alting sarrare, ax tole ————————————————————————————————————
Wafer thickness	180	200	220	μm	
Wafer size				μр	
Bump pitch		400		um	
Bump height		85		μm	
Bump diameter		110		μm	max tolerance = ±17

Figure 11 ■ Recommended Land Pattern for PE29102

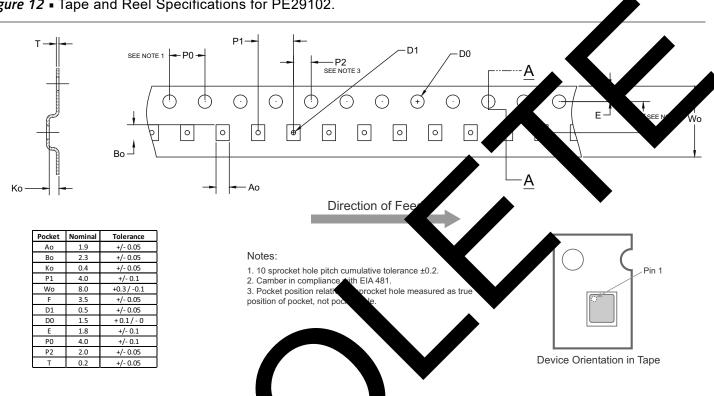




# **Tape and Reel Specification**

This section provides tape-and-reel information for the PE29102.

Figure 12 ■ Tape and Reel Specifications for PE29102.





## **Ordering Information**

Table 7 lists the available ordering code for the PE29102.

#### Table 7 ■ Order Code for PE29102

Order Codes	Description	Packaging	Shir ig Methr
PE29102A-X	PE29102 flip chip	Die on tape and reel	5 vits/7
PE29102A-Z	PE29102 flip chip	Die on tape and reel	3000 b. T&R

### **Document Categories**

#### Advance Information

The product is in a formative or design stage. The data set contains design target specifications for product development. Specifications and features may change in any manner with

#### Preliminary Specification

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